

Computing complete hyperbolic structures on cusped 3-manifolds

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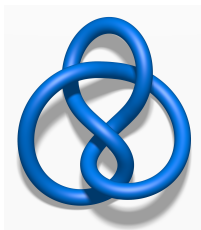


Figure-eight knot¹

Ambient isotopy

Continuous distortion of the ambient space.

¹[https://en.wikipedia.org/wiki/Figure-eight_knot_\(mathematics\)](https://en.wikipedia.org/wiki/Figure-eight_knot_(mathematics))

A brief history of knot censuses

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With several mistakes on the way...

3-Manifolds and knots

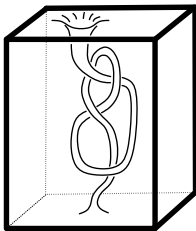
Gordon-Luecke theorem (1989)

The complements of two piecewise linear knots are homeomorphic if and only if the knots are equivalent.

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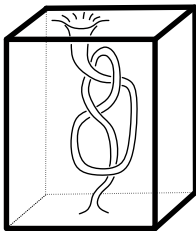
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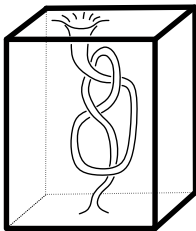


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→ We work with $S^3 \setminus K$. It is an open, orientable, cusped 3-manifold.

Theorem (Thurston)

Knots are either satellites, torus or hyperbolic.

Complete hyperbolic structures

Provides a hyperbolic metric on the manifold.

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Mostow rigidity

The geometry is unique.

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The hyperbolic volume

Great invariant linked to many theories and conjectures.

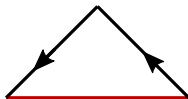
Outline

- 1 Ideal triangulations
- 2 The gluing equations
- 3 Casson and Rivin
- 4 Volume maximization
- 5 Combinatorial modifications

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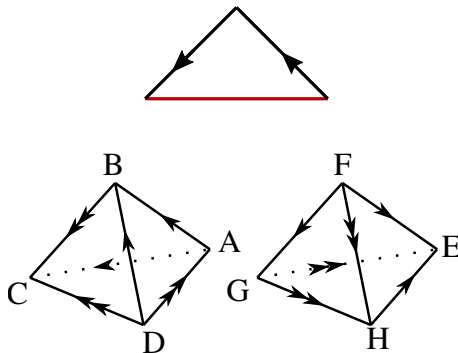
Generalized triangulations

Triangulated 3-manifolds with self-identifications.

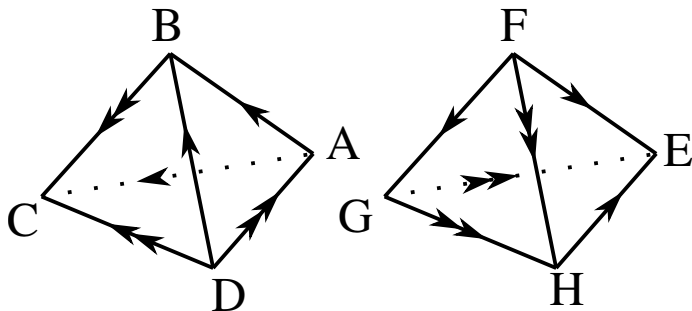


Generalized triangulations

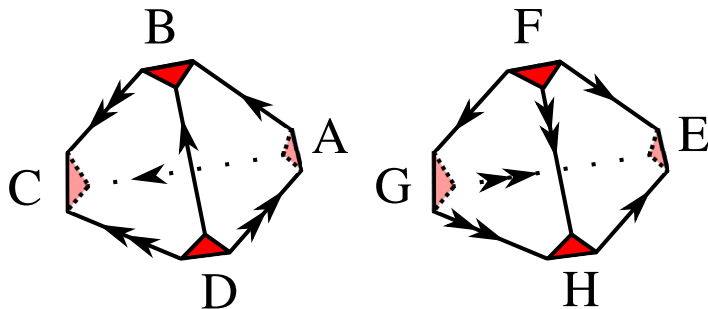
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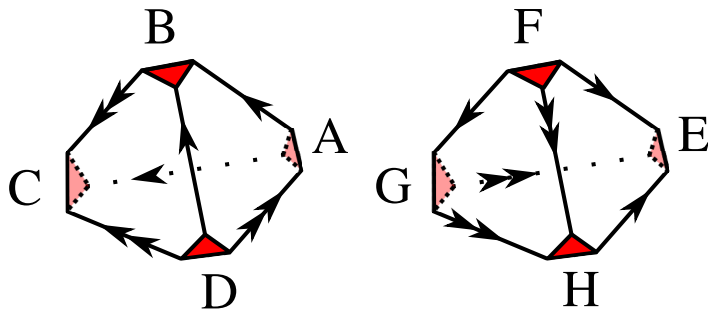
Knot complement triangulations



Knot complement triangulations

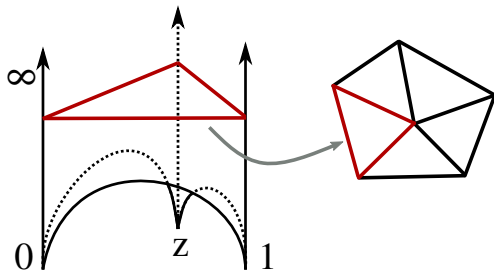


Knot complement triangulations



All 3-manifolds are triangulable, and there exists an algorithm for knots complements.

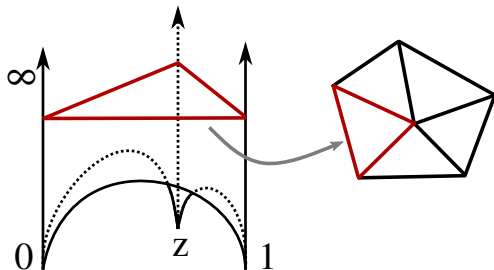
Hyperbolic ideal tetrahedra



Definition

A hyperbolic ideal tetrahedron is the convex hull of four distinct points on $\partial\mathbb{H}^3$.

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Either described with a single complex parameter or three dihedral angles.

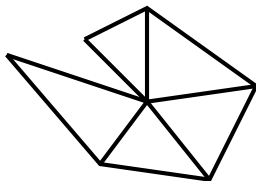
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Getting a hyperbolic manifold

Every point must have a neighborhood isometric to a sphere.

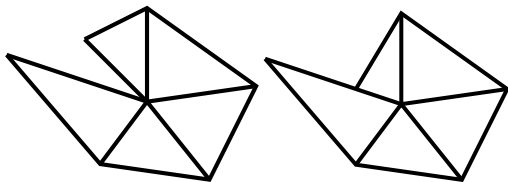
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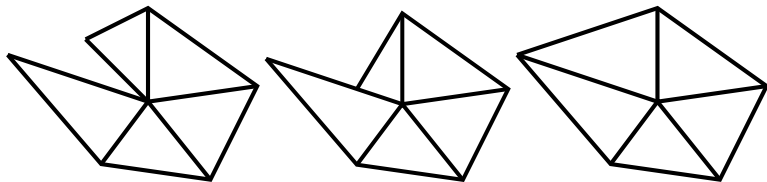
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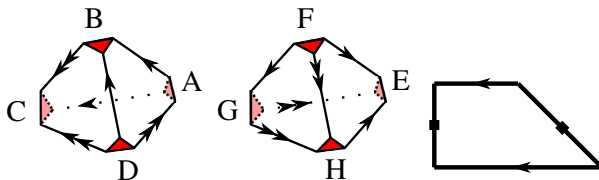


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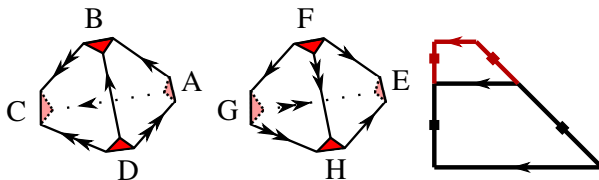
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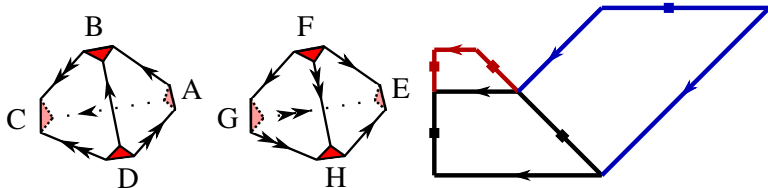
Completeness around the cusp



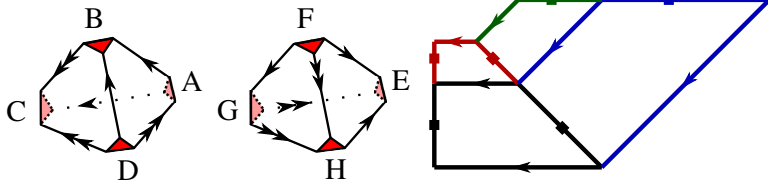
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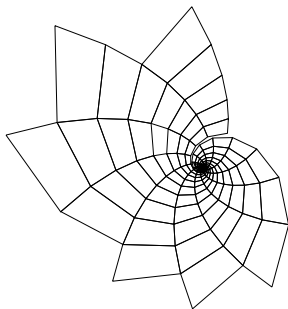
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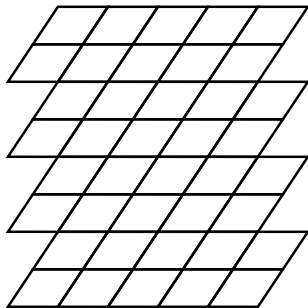
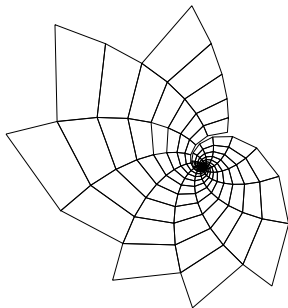
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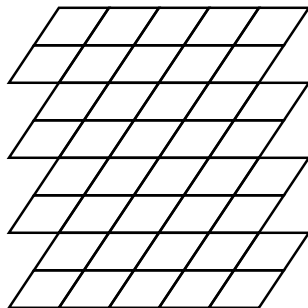
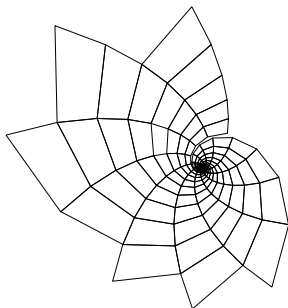
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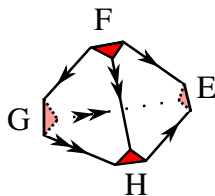
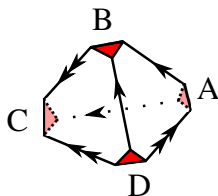
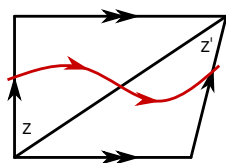


Theorem

The hyperbolic metric of the 3-manifold is complete if and only if the euclidean metric on the boundary torus is complete.

Normal curve

A sequence of segments cutting the triangles only by their edges.



Thurston gluing equations (1980)

Edge equations

$$\sum_i \log(z_i) = 2i\pi$$

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Complete hyperbolic structure problem

- Input: triangulation τ of a knot complement.
- Output: complete hyperbolic structure on τ .

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Complete hyperbolic structure problem

- Input: triangulation τ of a knot complement.
- ~~Output: complete hyperbolic structure on τ .~~
- Output: a triangulation equivalent to τ admitting a complete hyperbolic structure.

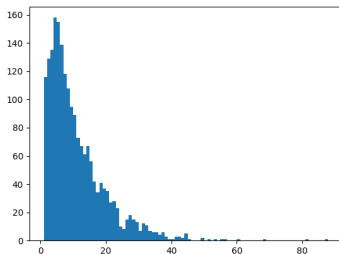


Uses Newton's method to directly solve Thurston's equations.



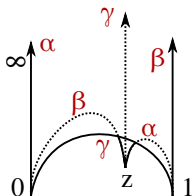
Uses Newton's method to directly solve Thurston's equations.

- No guarantees on the convergence speed.
- No studies of the failures cases.
- No methods/heuristics to find geometrizable triangulations.



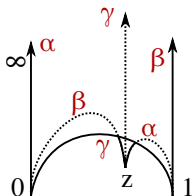
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The polytope of angle structures



- all angles are in $]0, \pi[$;
- the dihedral angles of the tetrahedra sum to π ;
- around each edge, the angles sum to 2π .

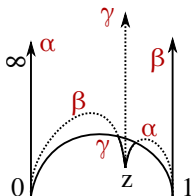
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Angle structures can be represented in $\mathbb{R}^{3|\tau|}$

Lemma (Neumann, 1992)

With τ the triangulation and $\mathcal{A}(\tau)$ the polytope of angle structures:

$$\dim \mathcal{A}(\tau) = |\tau| + |\partial M|$$

Existence of a hyperbolic metric

Theorem (Casson)

If $\mathcal{A}(\tau) \neq \emptyset$, then M admits a complete hyperbolic metric.

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Theorem (Casson, Rivin, 1994)

A point $p \in \mathcal{A}(\tau)$ corresponds to a complete hyperbolic metric on the interior of M if and only if p is a critical point of the volume functional $\mathcal{V} : \mathcal{A}(\tau) \rightarrow \mathbb{R}$.

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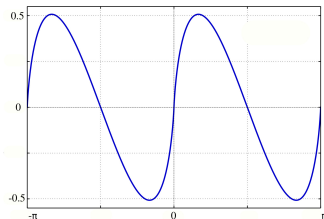
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Strategy \rightarrow maximize \mathcal{V} over $\mathcal{A}(\tau)$.

Volume of an angle structure

Lobachevsky function

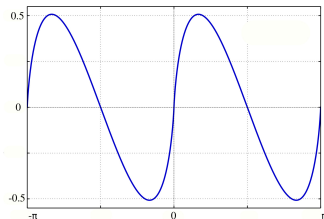
$$\mathcal{L}(x) = - \int_0^x \log |2 \sin t| dt$$



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Volume of an ideal tetrahedron

$$\mathcal{V}(\alpha, \beta, \gamma) = \mathcal{L}(\alpha) + \mathcal{L}(\beta) + \mathcal{L}(\gamma)$$

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Optimization problem

- Maximize \mathcal{V} over $\mathcal{A}(\tau)$.
- A base of $\mathcal{A}(\tau)$ can be easily computed.
- \mathcal{V} is the sum of the volumes of the tetrahedra.

Lemma (Rivin, 1994)

\mathcal{V} is strictly concave on a ideal hyperbolic tetrahedron.

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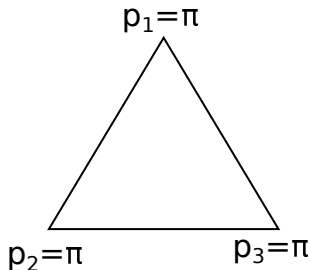
\mathcal{V} is strictly concave on a ideal hyperbolic tetrahedron.

- Let p_1 and p_2 the smallest angles of a tetrahedron T .
- Let w a linear transformation over the angles of T , with coefficients w_1 , w_2 and w_3 such that $w_1 + w_2 + w_3 = 0$.

$$-\frac{\partial^2 \mathcal{V}(T)}{\partial w^2} = \frac{(w_1 + w_2)^2 + (w_1 \cot p_1 - w_2 \cot p_2)^2}{\cot p_1 + \cot p_2}$$

The behavior of the volume

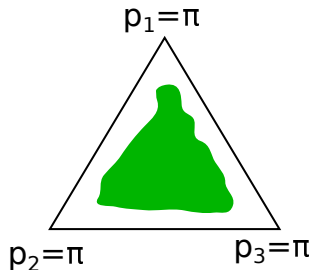
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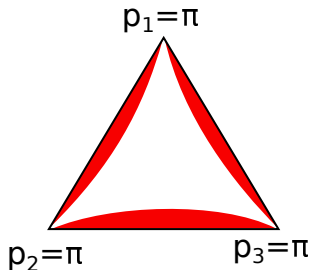
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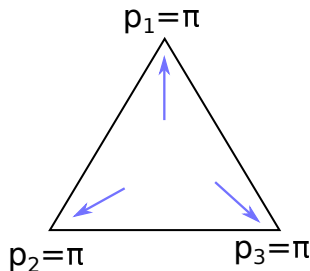
- If $\min(p_1, p_2)$ is constant, the derivatives are bounded by constants.
- If $\min(p_1, p_2) = x$ and $\max(p_1, p_2)$ is constant, then $\frac{\partial^2 \mathcal{V}(T)}{\partial w^2} = O_{x \rightarrow 0}(\frac{1}{x})$.



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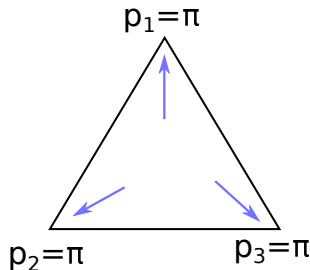
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- If $(p_1, p_2) \rightarrow (0, 0) \dots$



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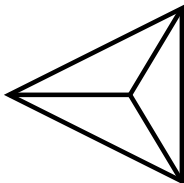
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- If $(p_1, p_2) \rightarrow (0, 0) \dots$ possible optimal on the boundary.



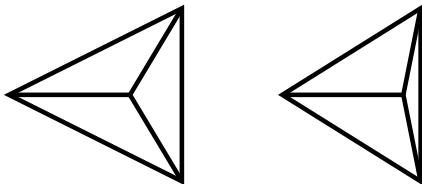
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What is happening?

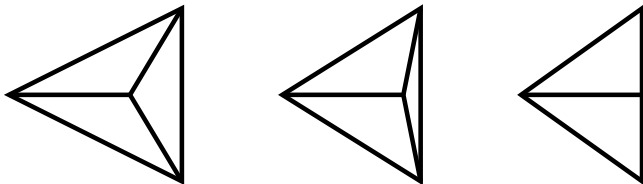
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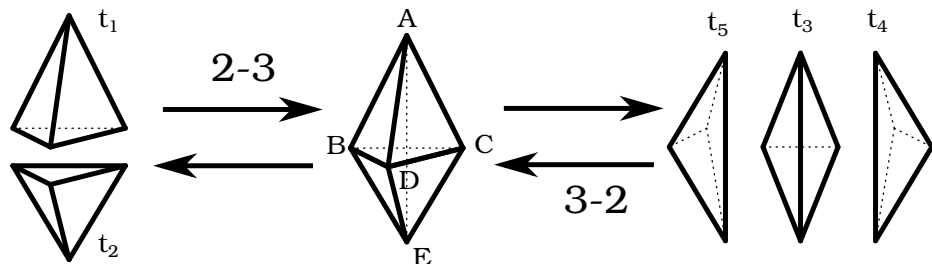


While (not geometric)
maximize volume
delete flat tetrahedra

Combinatorial modifications: Pachner moves

Theorem (Pachner,1991)

Any two triangulations of a 3-manifold can be linked by a sequence of Pachner moves.



Geometric Pachner moves

To try to preserve the geometric information.

Geometric Pachner move

Move between angle structures not modifying the tetrahedra not involved in the move.

Geometric Pachner moves

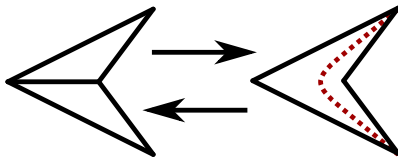
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Lemma

A 3-2 move is always geometric, a 2-3 is geometric iff the “external” angles are larger than π .



Geometric Pachner moves

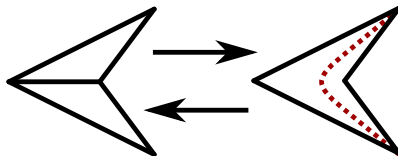
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Remark

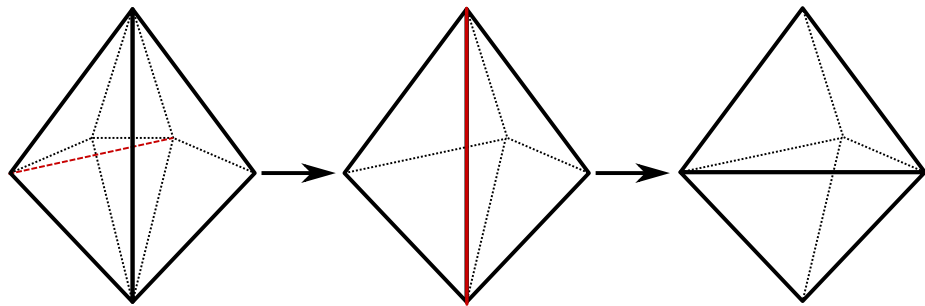
3-2 moves do not preserve the volume.

Flat tetrahedra deletion

Sequence of 2-3 moves followed by a 3-2.

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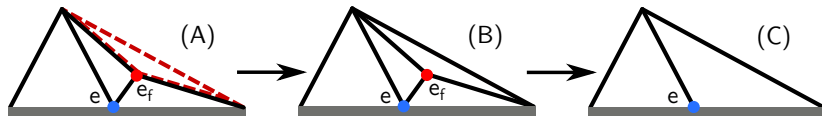


Recursive flat tetrahedra deletion

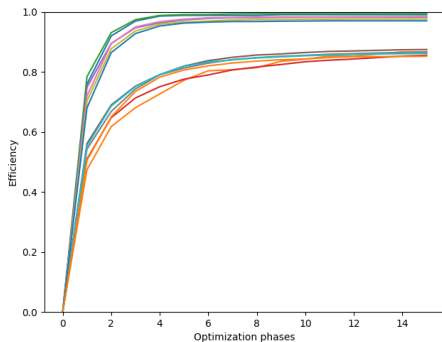
When no move is possible, we can still use our procedure.

Recursive flat tetrahedra deletion

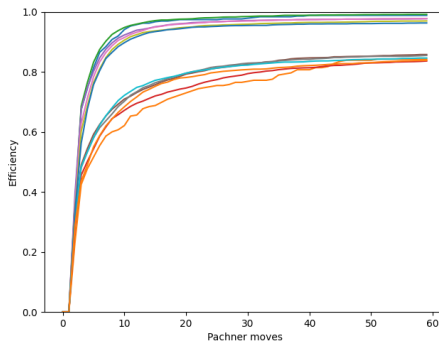
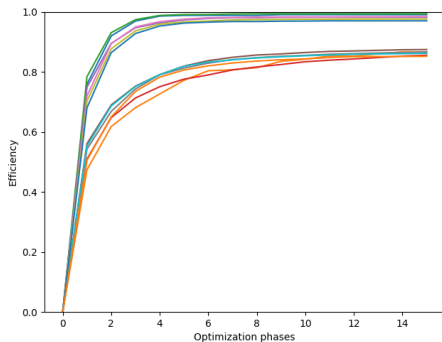
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In situation (A) we want to create the red tetrahedron to be in situation (B), where a 3-2 can be applied.

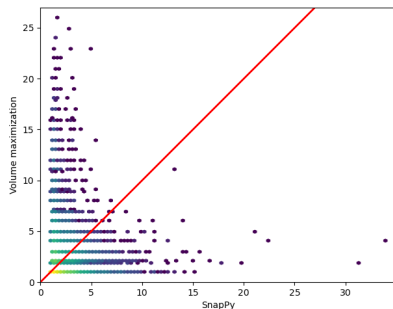


Right: Number of optimization phases required to find a complete hyperbolic structures.



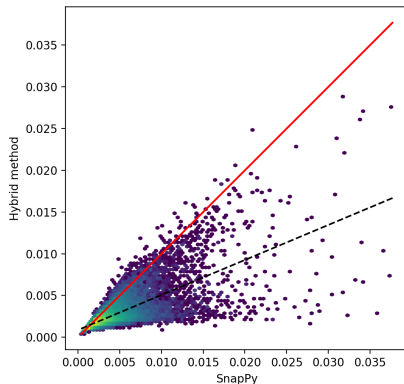
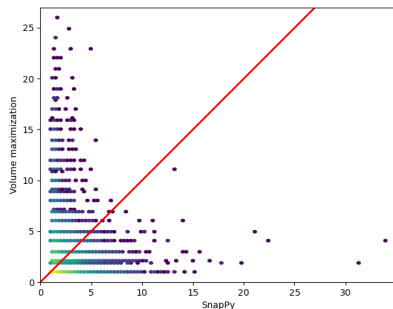
Right: Number of optimization phases required to find a complete hyperbolic structures. Left: Number of Pachner moves required to find a complete hyperbolic structures.

Results 2



Right: comparison of the difficult cases with SnapPy.

Results 2



Right: comparison of the difficult cases with SnapPy. Left: Time required to compute a complete hyperbolic structure in seconds, SnapPy compared to hybrid method.

Conclusion

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- To find a complete hyperbolic structure \rightarrow solve gluing equations;
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Results

- A lot of triangulations need few moves to accept complete hyperbolic structures;
- our method alone can be costly and not succeed;
- allows to improve on random re-triangulations when mixed.